

The Painlevé equations and q-Askey scheme

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This relation relies on the τ -function

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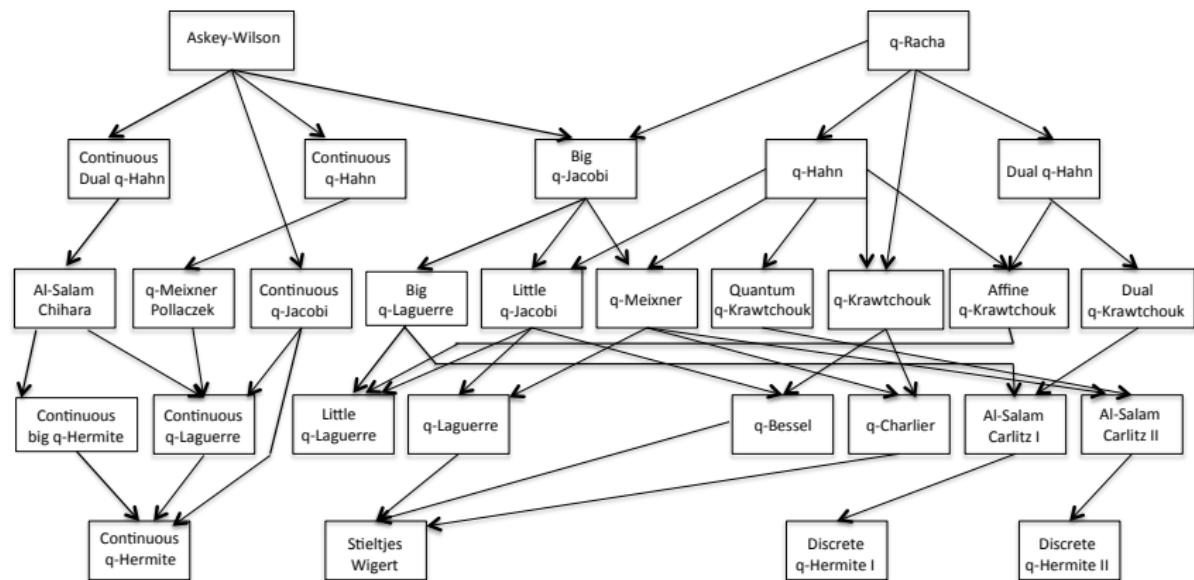
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- The eigenvalues of the q-difference operator are basic hypergeometric polynomials (q-Askey scheme).

M.M. arXiv:1307.6140

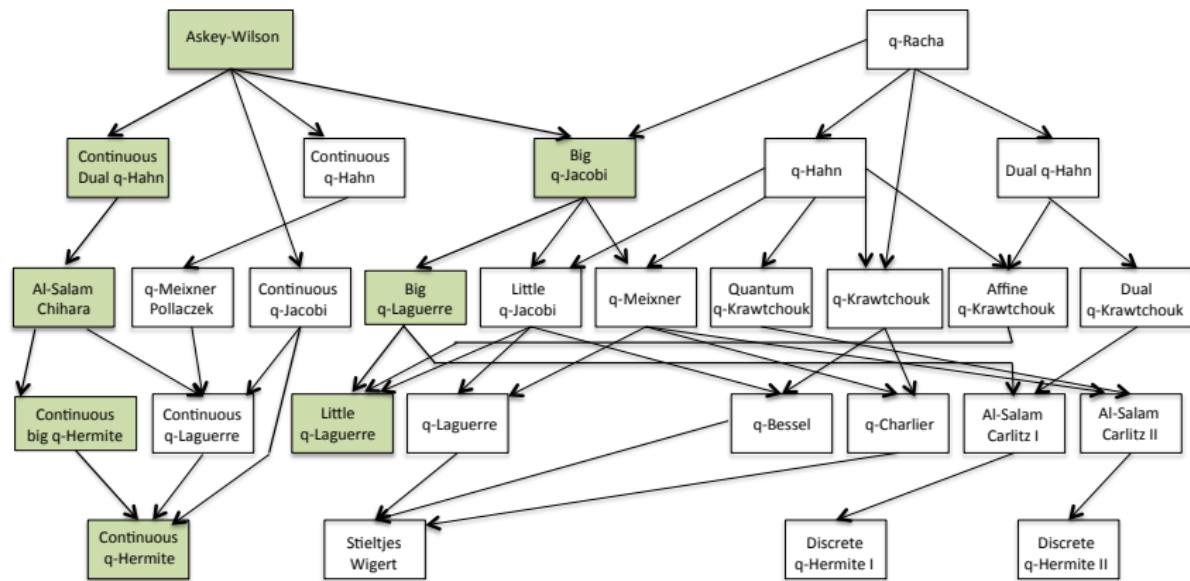
q-Askey scheme

Koekoek, Lesky, Swarttouw 2010

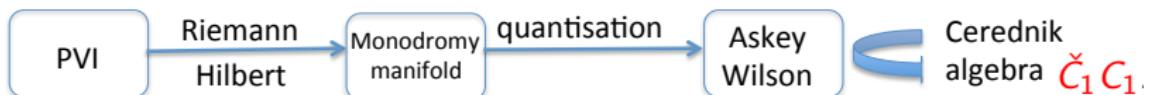


Painlevé equations and q-Askey polynomials

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Other results

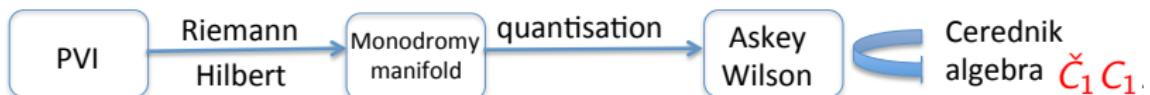


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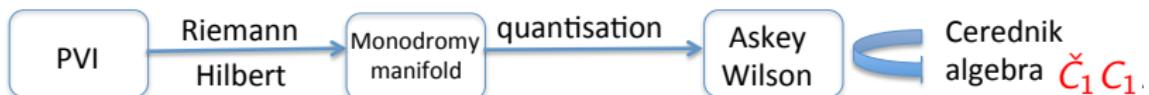
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- Confluence Cherednik algebra \Rightarrow seven new algebras. M.M.

arXiv:1307.6140

Cherednik algebra of type $\check{C}_1 C_1$

Cherednik '92, Sahi '99

Algebra generated by $V_0, V_1, \check{V}_0, \check{V}_1$:

$$(V_0 - k_0)(V_0 + k_0^{-1}) = 0$$

$$(V_1 - k_1)(V_1 + k_1^{-1}) = 0$$

$$(\check{V}_0 - u_0)(\check{V}_0 + u_0^{-1}) = 0$$

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$$\check{V}_1 V_1 V_0 \check{V}_0 = q^{-1/2},$$

k_0, k_1, u_0, u_1 scalars.

Spherical sub-algebra algebra:

choose a unipotent element: $e = \frac{1+\check{V}_1}{1+u_1^2},$

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$$e\mathcal{H}e = \langle X_1, X_2, X_3 \rangle$$

$$q^{-1/2}X_1X_2 - q^{1/2}X_2X_1 = (q^{-1} - q)X_3 - (q^{-1/2} - q^{1/2})\omega_3 e$$

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Casimir:

$$q^{\frac{1}{2}}X_2X_1X_3 - qX_2^2 - q^{-1}X_1^2 - qX_3^2 + q^{\frac{1}{2}}\omega_2 X_2 + q^{-\frac{1}{2}}\omega_1 X_1 + q^{\frac{1}{2}}\omega_3 X_3 = \omega_4 e.$$

Zhedanov '91, Oblomkov '04

Recap:

- Cherednik algebra of type $\check{C}_1 C_1$:

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Non-symmetric
Askey-Wilson (Sahi, Noumi-Stokman)

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Sixth Painlevé equation

$$\begin{aligned} y_{tt} &= \frac{1}{2} \left(\frac{1}{y} + \frac{1}{y-1} + \frac{1}{y-t} \right) y_t^2 - \left(\frac{1}{t} + \frac{1}{t-1} + \frac{1}{y-t} \right) y_t + \\ &+ \frac{y(y-1)(y-t)}{t^2(t-1)^2} \left[\alpha + \beta \frac{t}{y^2} + \gamma \frac{t-1}{(y-1)^2} + \delta \frac{t(t-1)}{(y-t)^2} \right]. \end{aligned}$$

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Singular points at $0, 1, \infty$.

Parameters $\alpha, \beta, \gamma, \delta$.

All Painlevé equations are **isomonodromic deformation equations** (Jimbo-Miwa 1980)

$$\frac{dB}{d\lambda} - \frac{dA}{dt} = [A, B]$$

$$A = A(\lambda; t, y, y_t), B = B(\lambda; t, y, y_t) \in \mathfrak{sl}_2.$$

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This means that **the monodromy data** of the linear system

$$\frac{dY}{d\lambda} = A(\lambda; t, y, y_t)Y$$

are **locally constant along solutions of the Painlevé equation**.

PVI as isomonodromic deformations

$$\frac{d}{d\lambda} Y = \sum_{k=1}^3 \frac{A_k}{\lambda - a_k} Y, \quad \lambda \in \mathbb{C} \setminus \{a_1, a_2, a_3\}$$

$A_1, A_2, A_3 \in \mathfrak{sl}(2, \mathbb{C})$, $\sum_{k=1}^3 A_k = -A_\infty$, diagonal.

- Fundamental matrix: $Y_\infty(\lambda) = (1 + O(\frac{1}{\lambda})) \lambda^{-A_\infty}$
- Monodromy matrices: $\gamma_j(Y_\infty) = Y_\infty M_j$

eigenvalues of M_j are $\exp(\pm \frac{p_j}{2})$, $i = 1, 2, 3, \infty$,

$M_\infty M_1 M_2 M_3 = 1$.

Jimbo, Miwa '81

Cherednik algebra as quantisation of the monodromy group

$$(M_3 - e^{\frac{p_3}{2}})(M_3 - e^{-\frac{p_3}{2}}) = 0,$$

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There is a natural quantisation which works.

$$M_1 \rightarrow i\check{V}_1, \quad M_2 \rightarrow iV_1, \quad M_3 \rightarrow iV_0, \quad M_\infty \rightarrow i\check{V}_0.$$

$$u_1 = -ie^{-\frac{p_1}{2}}, \quad k_0 = -ie^{-\frac{p_3}{2}}, \quad k_1 = -ie^{-\frac{p_2}{2}}, \quad u_0 = -ie^{-\frac{p_\infty}{2}}.$$

Monodromy manifold for PVI

Riemann Hilbert correspondence: $\forall (M_1, M_2, M_3) / SL_2(\mathbb{C})$ there exists a unique local solution to PVI modulo Okamoto transformations.

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The relation $M_\infty M_3 M_2 M_1 = 1$ gives:

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This cubic is the moduli space of monodromy representations:

$$\rho : \pi_1(\overline{\mathbb{C}} \setminus \{0, t, 1, \infty\}) \rightarrow SL_2(\mathbb{C}).$$

Monodromy manifold and spherical sub-algebra

Natural Poisson bracket on

$$x_1 x_2 x_3 + x_1^2 + x_2^2 + x_3^2 + \omega_1 x_1 + \omega_2 x_2 + \omega_3 x_3 - \omega_4 = 0,$$

defines a natural Poisson bracket:

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....cyclic...

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- Complexify the flat coordinates to describe the character variety.
- Quantise flat coordinates.

Poincaré uniformisation

$$\Sigma = \mathbb{H}/\Delta,$$

where Δ is a *Fuchsian group*, i.e. a discrete sub-group of $\mathbb{P}SL_2(\mathbb{R})$.

Poincaré uniformisation

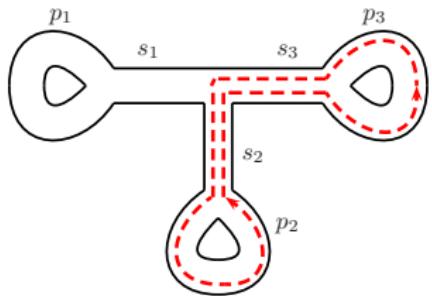
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Decompose each hyperbolic element in Right, Left and Edge matrices

Fock, Thurston

$$R := \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix}, \quad L := \begin{pmatrix} 0 & 1 \\ -1 & -1 \end{pmatrix}, \quad X_y := \begin{pmatrix} 0 & -e^{\frac{y}{2}} \\ e^{-\frac{y}{2}} & 0 \end{pmatrix}.$$



Teichmüller space of a Riemann sphere with 4 singularities

Interpret each x_i as a geodesic length:

$$\begin{aligned}x_1 &= e^{s_2+s_3} + e^{-s_2-s_3} + e^{-s_2+s_3} + (e^{\frac{p_2}{2}} + e^{-\frac{p_2}{2}})e^{s_3} + (e^{\frac{p_3}{2}} + e^{-\frac{p_3}{2}})e^{-s_2} \\x_2 &= e^{s_3+s_1} + e^{-s_3-s_1} + e^{-s_3+s_1} + (e^{\frac{p_3}{2}} + e^{-\frac{p_3}{2}})e^{s_1} + (e^{\frac{p_1}{2}} + e^{-\frac{p_1}{2}})e^{-s_3} \\x_3 &= e^{s_1+s_2} + e^{-s_1-s_2} + e^{-s_1+s_2} + (e^{\frac{p_1}{2}} + e^{-\frac{p_1}{2}})e^{s_2} + (e^{\frac{p_2}{2}} + e^{-\frac{p_2}{2}})e^{-s_1}\end{aligned}$$

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Complexify $s_1, s_2, s_3 \Rightarrow$ flat coordinates on the Character variety.

Quantisation:

$s_i \rightarrow$ quantum operator s_i^\hbar with commutation relation

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\Rightarrow Weyl ordering:

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$$\exp(s_i^\hbar) \exp(s_j^\hbar) = \exp\left(s_i^\hbar + s_j^\hbar + \frac{1}{2}[s_i^\hbar, s_j^\hbar]\right),$$

Quantum algebra. Zhedanov algebra $q = e^{-i\pi\hbar}$:

$$\begin{aligned} q^{-1/2}x_1^\hbar x_2^\hbar - q^{1/2}x_2^\hbar x_1^\hbar &= (q^{-1} - q)x_3^\hbar + (q^{-1/2} - q^{1/2})\omega_3 \\ q^{-1/2}x_2^\hbar x_3^\hbar - q^{1/2}x_3^\hbar x_2^\hbar &= (q^{-1} - q)x_1^\hbar + (q^{-1/2} - q^{1/2})\omega_1 \\ q^{-1/2}x_3^\hbar x_1^\hbar - q^{1/2}x_1^\hbar x_3^\hbar &= (q^{-1} - q)x_2^\hbar + (q^{-1/2} - q^{1/2})\omega_2 \end{aligned}$$

(L. Chekhov and M.M. J.Phys A 2010).

Quantise the monodromy matrices: each monodromy matrix corresponds to a half-geodesic on our Riemann surface.

Quantise the monodromy matrices: each monodromy matrix corresponds to a half-geodesic on our Riemann surface.

Quantise them in the same way: we obtain the Cherednik algebra of type $\check{C}_1 C_1$ (M.M. arXiv:1307.6140)

$$M_1 \rightarrow i\check{V}_1, \quad M_2 \rightarrow iV_1, \quad M_3 \rightarrow iV_0, \quad M_\infty \rightarrow i\check{V}_0.$$

$$u_1 = -ie^{-\frac{p_1}{2}}, \quad k_0 = -ie^{-\frac{p_3}{2}}, \quad k_1 = -ie^{-\frac{p_2}{2}}, \quad u_0 = -ie^{-S_1-S_2-S_3}.$$

Embedding of the Cherednik algebra of type $\check{C}_1 C_1$ into $Mat(2, \mathbb{T}_q)$

$$\cdot \quad V_0 = \begin{pmatrix} k_0 - k_0^{-1} - ie^{-s_3} & -ie^{-s_3} \\ k_0^{-1} - k_0 + ie^{-s_3} + ie^{s_3} & ie^{-s_3} \end{pmatrix},$$

$$V_1 = \begin{pmatrix} k_1 - k_1^{-1} - ie^{s_2} & k_1 - k_1^{-1} - ie^{-s_2} - ie^{s_2} \\ ie^{s_2} & ie^{s_2} \end{pmatrix},$$

$$\check{V}_1 = \begin{pmatrix} 0 & -ie^{s_1} \\ ie^{-s_1} & u_1 - u_1^{-1} \end{pmatrix}, \quad \check{V}_0 = \begin{pmatrix} u_0 & 0 \\ s & -\frac{1}{u_0} \end{pmatrix},$$

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$$e^{S_2} e^{S_1} = q e^{S_1} e^{S_2}, \quad e^{S_3} e^{S_2} = q e^{S_2} e^{S_3}, \quad e^{S_1} e^{S_3} = q e^{S_3} e^{S_1}.$$

Monodromy manifolds for the Painlevé equations

$$PVI \quad x_1x_2x_3 + x_1^2 + x_2^2 + x_3^2 + \omega_1x_1 + \omega_2x_2 + \omega_3x_3 = \omega_4$$

$$PV \quad x_1x_2x_3 + x_1^2 + x_2^2 + \omega_1x_1 + \omega_2x_2 + \omega_3x_3 = \omega_4$$

$$PIV \quad x_1x_2x_3 + x_1^2 + \omega_1x_1 + \omega_2x_2 + \omega_3x_3 + 1 = \omega_4$$

$$PIII \quad x_1x_2x_3 + x_1^2 + x_2^2 + \omega_1x_1 + \omega_2x_2 = \omega_1 - 1$$

$$PII \quad x_1x_2x_3 + x_1 + x_2 + x_3 = \omega_4$$

$$PI \quad x_1x_2x_3 + x_1 + x_2 + 1 = 0$$

The confluence from PVI to PV is realised by

$$s_3 \rightarrow s_3 - \log[\epsilon], \quad p_3 \rightarrow p_3 - 2 \log[\epsilon], \quad \epsilon \rightarrow 0$$

$$x_1 = -e^{s_2+s_3} - e^{-s_2+s_3} - (e^{\frac{p_2}{2}} + e^{-\frac{p_2}{2}})e^{s_3} - e^{\frac{p_3}{2}}e^{-s_2}$$

$$x_2 = -e^{s_3+s_1} - e^{\frac{p_3}{2}}e^{s_1},$$

$$x_3 = -e^{s_1+s_2} - e^{-s_1-s_2} - e^{-s_1+s_2} - (e^{\frac{p_1}{2}} + e^{-\frac{p_1}{2}})e^{s_2} - (e^{\frac{p_2}{2}} + e^{-\frac{p_2}{2}})e^{-s_1}$$

$$x_1 x_2 x_3 + x_1^2 + x_2^2 + \omega_1 x_1 + \omega_2 x_2 + \omega_3 x_3 = \omega_4$$

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$$x_1 x_2 x_3 + x_1^2 + x_2^2 + \omega_1 x_1 + \omega_2 x_2 + \omega_3 x_3 = \omega_4$$

Quantum PV algebra:

$$q^{-1/2} x_1^\hbar x_2^\hbar - q^{1/2} x_2^\hbar x_1^\hbar = (q^{-1/2} - q^{1/2})\omega_3$$

$$q^{-1/2} x_2^\hbar x_3^\hbar - q^{1/2} x_3^\hbar x_2^\hbar = (q^{-1} - q)x_1^\hbar + (q^{-1/2} - q^{1/2})\omega_1$$

$$q^{-1/2} x_3^\hbar x_1^\hbar - q^{1/2} x_1^\hbar x_3^\hbar = (q^{-1} - q)x_2^\hbar + (q^{-1/2} - q^{1/2})\omega_2$$

$$V_0 = \begin{pmatrix} -1 & 0 \\ 1 + i e^{S_3} & 0 \end{pmatrix}, \quad V_0^2 + V_0 = 0$$

$$V_1 = \begin{pmatrix} k_1 - k_1^{-1} - i e^{S_2} & k_1 - k_1^{-1} - i e^{-S_2} - i e^{S_2} \\ i e^{S_2} & i e^{S_2} \end{pmatrix},$$

$$\check{V}_1 = \begin{pmatrix} 0 & -ie^{S_1} \\ i e^{-S_1} & u_1 - u_1^{-1} \end{pmatrix},$$

$$\check{V}_0 = \begin{pmatrix} 0 & 0 \\ s & -\frac{1}{u_0} \end{pmatrix}, \quad \check{V}_0^2 + u_0^{-1} \check{V}_0 = 0$$

$$q^{1/2} \check{V}_1 V_1 V_0 = \check{V}_0 + u_0^{-1},$$

$$q^{1/2} \check{V}_0 \check{V}_1 V_1 = V_0 + 1.$$

\mathcal{H}_V :

$$V_0^2 + V_0 = 0,$$

$$(V_1 - k_1)(V_1 + k_1^{-1}) = 0,$$

$$\check{V}_0^2 + u_0^{-1} \check{V}_0 = 0,$$

$$(\check{V}_1 - u_1)(\check{V}_1 + u_1^{-1}) = 0,$$

$$q^{1/2} \check{V}_1 V_1 V_0 = \check{V}_0 + u_0^{-1},$$

$$q^{1/2} \check{V}_0 \check{V}_1 V_1 = V_0 + 1.$$

\mathcal{H}_V :

$$\begin{aligned} V_0^2 + V_0 &= 0, \\ (V_1 - k_1)(V_1 + k_1^{-1}) &= 0, \\ \check{V}_0^2 + u_0^{-1}\check{V}_0 &= 0, \\ (\check{V}_1 - u_1)(\check{V}_1 + u_1^{-1}) &= 0, \\ q^{1/2}\check{V}_1 V_1 V_0 &= \check{V}_0 + u_0^{-1}, \\ q^{1/2}\check{V}_0 \check{V}_1 V_1 &= V_0 + 1. \end{aligned}$$

- Represented on the space of Laurent polynomials.
- Non-symmetric continuous dual q-Hahn polynomials. M.M. SIGMA
2014
- Spherical sub-algebra represented on the space of symmetric Laurent polynomials.

PIV:

$$\begin{aligned} V_0^2 + V_0 = 0, \\ (V_1 - k_1)(V_1 + k_1^{-1}) = 0, \end{aligned}$$

$$\check{V}_1^2 + u_1^{-1} \check{V}_1 = 0,$$

$$\check{V}_0^2 + \check{V}_0 = 0,$$

$$\check{V}_1 V_1 V_0 = \frac{\check{V}_0 + 1}{\sqrt{q}},$$

$$\check{V}_0 \check{V}_1 = 0,$$

$$V_0 \check{V}_0 = 0,$$

PII:

$$\begin{aligned} V_0^2 + V_0 = 0, \\ \check{V}_1^2 + V_1 = 0, \end{aligned}$$

$$\check{V}_1^2 + u_1^{-1} \check{V}_1 = 0,$$

$$\check{V}_0^2 + \check{V}_0 = 0,$$

$$\check{V}_1 V_1 V_0 = \frac{\check{V}_0 + 1}{\sqrt{q}},$$

$$\check{V}_0 \check{V}_1 = 0,$$

$$V_0 \check{V}_0 = 0,$$

PI:

$$V_0^2 = 0,$$

$$V_1^2 + V_1 = 0,$$

$$\check{V}_1^2 + \check{V}_1 = 0,$$

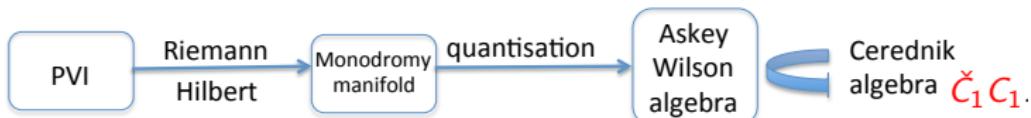
$$\check{V}_0^2 + \check{V}_0 = 0,$$

$$\check{V}_1 V_1 V_0 = \frac{\check{V}_0 + 1}{\sqrt{q}},$$

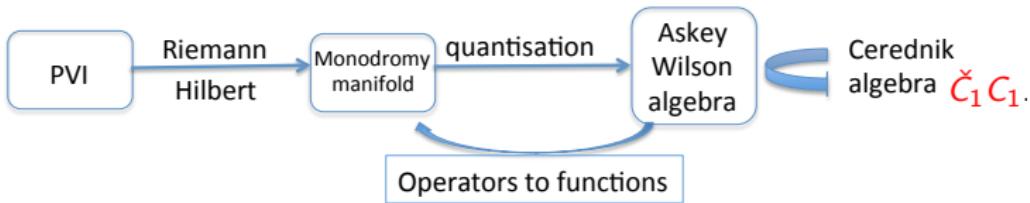
$$\check{V}_0 \check{V}_1 = 0,$$

$$V_0 \check{V}_0 = 0,$$

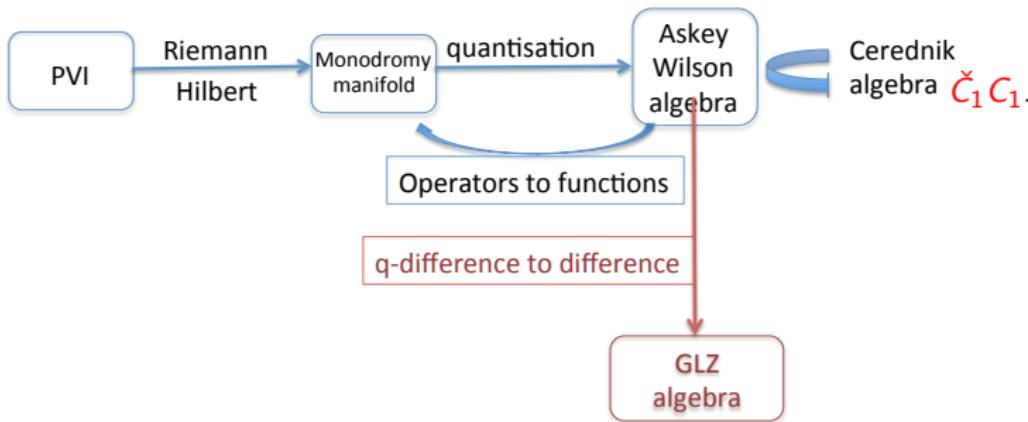
Outlook



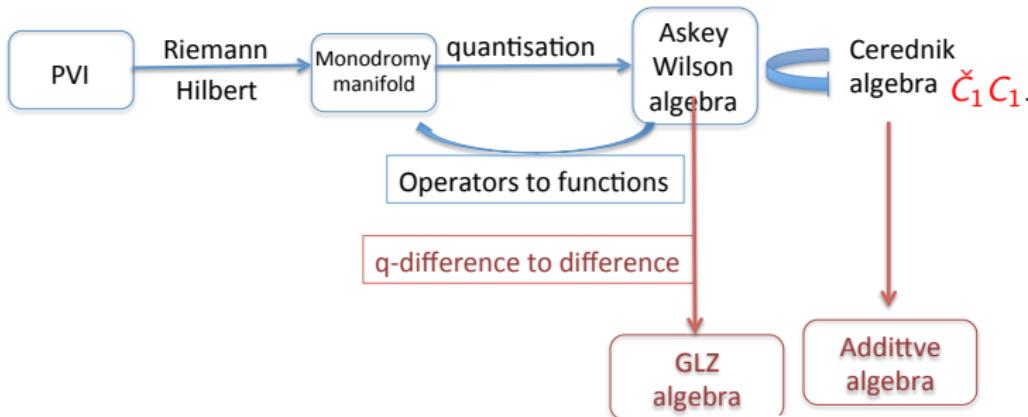
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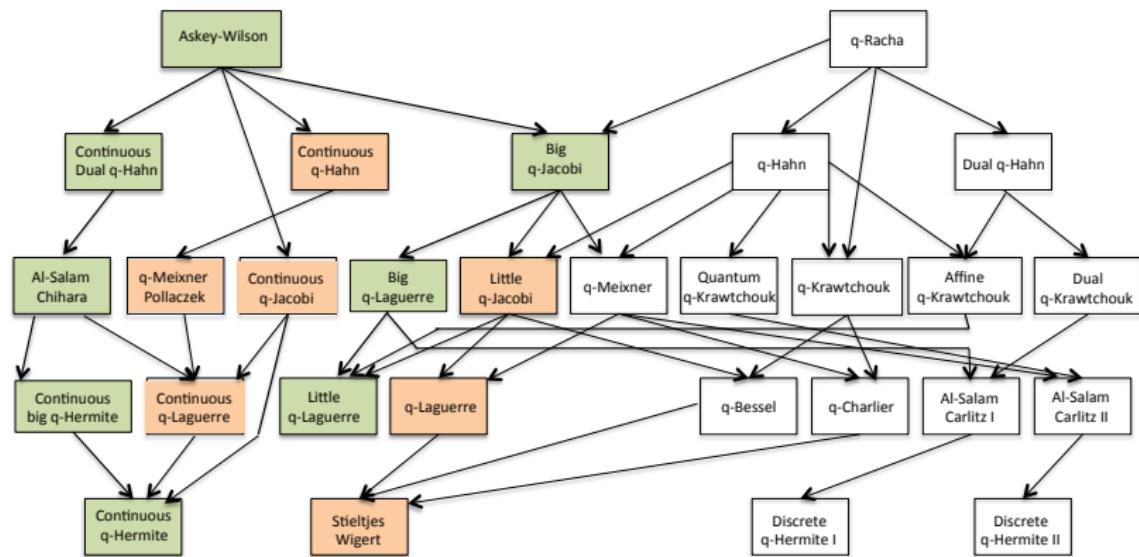


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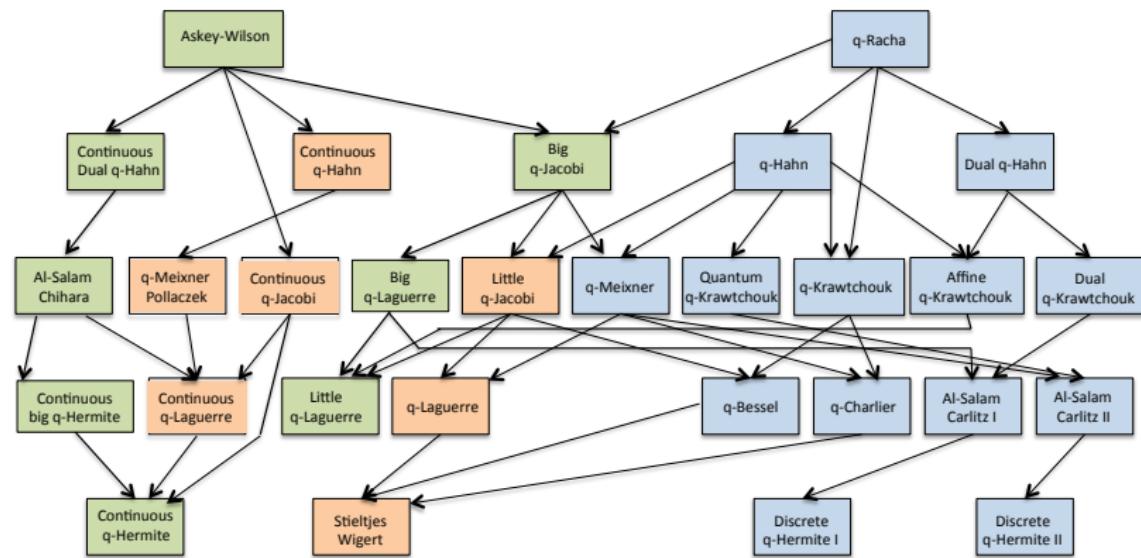


$$\begin{aligned}
 v_0^2 + \frac{(\delta + \gamma - 1)^2}{4} &= 0, \\
 \check{v}_0^2 + \frac{(\delta - \gamma)^2}{4} &= 0, \\
 v_1^2 + \frac{(\alpha - \beta)^2}{4} &= 0, \\
 \check{v}_1^2 + \frac{(\alpha + \beta)^2}{4} &= 0,
 \end{aligned}$$

Outlook



Outlook



Outlook

- Additive discrete Painlevé equations

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- q-difference and elliptic Painlevé equations may correspond to elliptic hypergeometric bi-orthogonal polynomials.
- Multivariable high order analogues of the Painlevé equations
→ *confluence scheme for Macdonald polynomials*