

Several dynamics for the Painlevé V foliation

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joint work with J.P. Ramis

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Web seminar on Painlevé equations and related topics

Introduction

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We present here the main tools in the case of the Painlevé V foliation.

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- the isomonodromic property: all the Painlevé equations appear as a (generalized) isomonodromic condition on some space of linear rank 2 connections on a basis;
- the hamiltonian property: the Painlevé vector fields can be written on $T \times C^2$ under a hamiltonian form [Okamoto]:

$$\begin{cases} \dot{p} = -\frac{\partial H_{\bullet}}{\partial q} \\ \dot{q} = \frac{\partial H_{\bullet}}{\partial p} \end{cases}$$

with $H_{\bullet} = H(p, q, t, \theta)$, $t \in T = \mathbb{P}^1 \setminus \{\text{fixed sing.}\}$, θ : parameters.

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Dynamics through RH_{VI} induced by $Aut(\pi_1^{VI})$: generated by 3 braids. In trace coordinates:

$$h_{1,2} : \begin{cases} x'_1 = -x_1 - x_2 x_3 + b_1 \\ x'_2 = -x_2 + x_1 x_3 + x_2 x_3^2 - b_1 x_3 + b_2 \\ x'_3 = x_3 \end{cases}$$

This is a *tame* dynamics: $h_{i,j}$ and $h_{i,j}^{-1}$ are polynomials dynamics.

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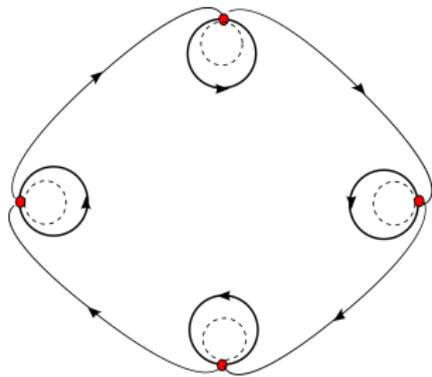
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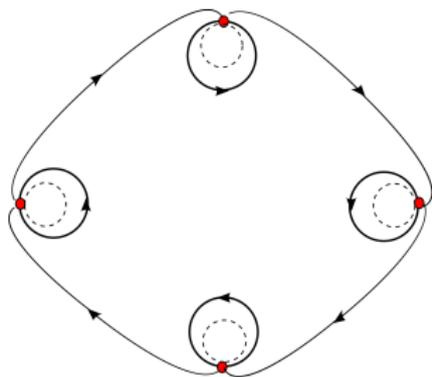
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The groupoid $\pi_1^{VI}(X, S)$



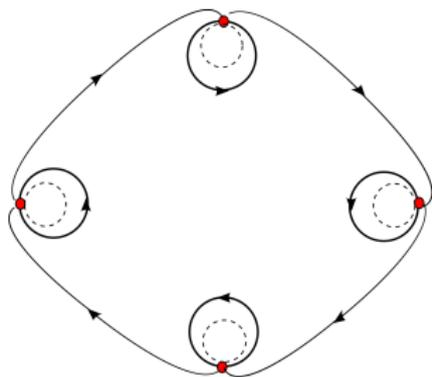
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Linear representation ρ of the groupoid:

- objects (base point) $s \rightarrow \rho(s) = 2 \text{ dim vector space } V_s$ (RH: local matrix solution Y_s);
- morphisms (paths up to homotopy) $\gamma_{s,t} \rightarrow \rho(\gamma_{s,t}) = \text{a linear map from } V_s \text{ to } V_t$ (RH: $M(\gamma_{s,t})$ induced by analytic continuation of local matrix solutions:
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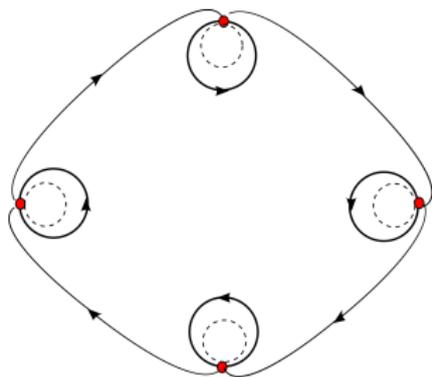
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A change of representation of the objects gives an equivalent representation:

$$\rho' \sim \rho \Leftrightarrow \forall s, \exists M_s, M'(\gamma_{s,t}) = M_s \cdot M(\gamma_{s,t}) \cdot M_t.$$

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Definition. Let γ be some path in $\pi_1^{VI}(X, S)$ from s_i to s_j , $\gamma_{i,i}$ the local loops at the extremities.

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Some intersections of these lines correspond to special solutions studied by K. Kaneko.

The Painlevé V equation as isomonodromic deformations of linear systems

$$\mathcal{M}_V = \left\{ \frac{dY}{dx} = \left(\frac{A_0}{x - s_0} + \frac{A_1}{x - s_1} + A_\infty \right) \cdot Y \right\} // (Y \rightarrow YP, x \rightarrow \varphi(x)).$$

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Around $z = x^{-1} = 0$, formally,

$$\frac{d\hat{Y}}{dz} = \left(\frac{Q}{z^2} + \frac{L}{z} \right) \cdot \hat{Y}, \quad Q, L \text{ diagonal.}$$

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Formal solutions around ∞ :

$$\hat{Y}(z) = \hat{F}(z) z^L \exp Q/z.$$

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- The gauge quotient:

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under the action of D (diagonal matrices) and $P = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$.

Invariant coordinates :

$\alpha_0 = \det(A_0)$, $\alpha_1 = \det(A_1)$, $\alpha_\infty = \det(L) = (a_0 + a_1)^2$; ("local" coordinates);

$\tau = a_0 t$ (the "time" coordinate);

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- The quotient under $Aut(P^1)$:

Using a translation on x : $s_0 = 0$ ($s_1 \neq 0$);

Action of $x \rightarrow \mu x$: $(\tau, \beta_0, \beta_1, s_1^{-1}) \rightarrow (\mu\tau, \beta_0, \mu\beta_1, \mu s_1^{-1})$.

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The method of H. Chiba in order to compactify the variety on which live the Painlevé foliations can also be used starting from the spaces of linear connections.

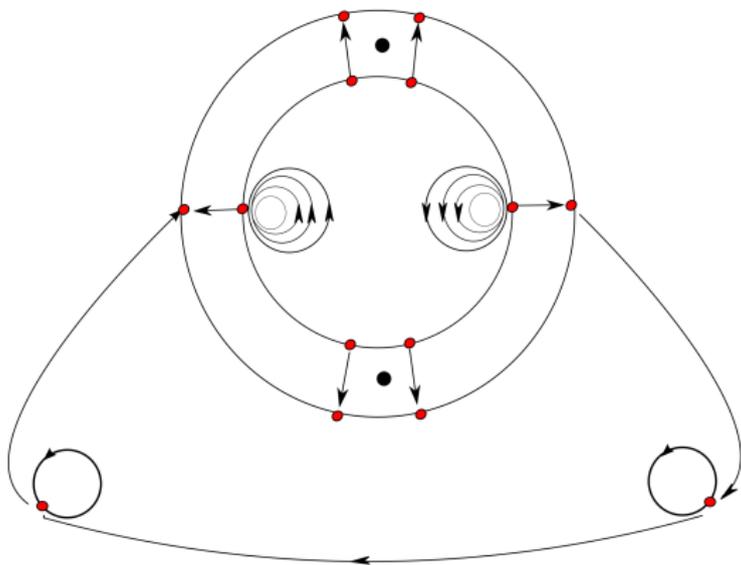
The wild character variety χ_V

- The *monodromy operators* are defined by the analytic continuation of the matrix solutions along paths. They define a representation of the group $\pi_1(P_1 \setminus S, x_0)$ or of a fundamental groupoid with 3 base points.
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 - The *Stokes operators* are defined by the comparison between two resummations of a formal matrix solution \hat{Y} on the left and rightside of a singular direction.
 - The *exponential torus* is an action of the algebraic group (\mathbb{C}^*, \times) on the local formal solutions.
- Any element of \mathcal{M}_V defines a representation of the following extended groupoid:

The wild fundamental groupoid $\pi_1^V(X, S)$



with topological relations and additional wild relations

$$t_{i,i}(\kappa\kappa') = t_{i,i}(\kappa) \cdot t_{i,i}(\kappa') \quad i=0,1;$$

$$[\widehat{\gamma}_{i,i}, t_{i,i}(\kappa)] = \star_i$$

$$[[\sigma_i, t_{i,i}(\kappa)], \sigma_i] = \star_i \quad (\sigma_i: \text{Stokes loops based in } s_i).$$

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- Such representation satisfies the property (\star): there exists a Borel-Cartan configuration (B^-, C, B^+) such that:

$$\rho(\mathfrak{t}_{1,1}(\kappa)) = C, \quad \rho(\sigma_1) \in U^-, \quad \rho(\widehat{\gamma}'_{1,2} \cdot \sigma_2 \cdot \widehat{\gamma}'_{2,1}) \in U^+.$$

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The character variety χ_V is the variety of equivalent representations in $SL_2(\mathbb{C})$ of $\pi_1^V(X, S)$ which satisfy (\star).

A class of such representations is "quasi" characterized by the data

$$\rho(\sigma_1) = U_1 = \begin{pmatrix} 1 & 0 \\ u_1 & 1 \end{pmatrix}, \quad \rho(\sigma_2) = U_2 = \begin{pmatrix} 1 & u_2 \\ 0 & 1 \end{pmatrix}, \quad \rho(\widehat{\gamma}_{1,1}) = M_0 = \begin{pmatrix} e_0 & 0 \\ 0 & e_0^{-1} \end{pmatrix}$$

$$\text{and } \rho(\gamma_{3,3}) = M_3, \quad \rho(\gamma_{4,4}) = M_4.$$

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- Any connection in \mathcal{M}_V induces a linear representation of the groupoid $\pi_1^V(X, S)$: the paths are represented either by analytic continuation of local solution or by resummation process for a ray.
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$$\rho(\mathbf{t}_{1,1}(\kappa)) = C, \quad \rho(\sigma_1) \in U^-, \quad \rho(\widehat{\gamma}'_{1,2} \cdot \sigma_2 \cdot \widehat{\gamma}'_{2,1}) \in U^+.$$

The character variety χ_V is the variety of equivalent representations in $SL_2(\mathbb{C})$ of $\pi_1^V(X, S)$ which satisfy (\star).

A class of such representations is "quasi" characterized by the data

$$\rho(\sigma_1) = U_1 = \begin{pmatrix} 1 & 0 \\ u_1 & 1 \end{pmatrix}, \quad \rho(\sigma_2) = U_2 = \begin{pmatrix} 1 & u_2 \\ 0 & 1 \end{pmatrix}, \quad \rho(\widehat{\gamma}_{1,1}) = M_0 = \begin{pmatrix} e_0 & 0 \\ 0 & e_0^{-1} \end{pmatrix}$$

$$\text{and } \rho(\gamma_{3,3}) = M_3, \quad \rho(\gamma_{4,4}) = M_4.$$

Indeed from the local relations we have either $\rho(\mathbf{t}_{1,1}(\kappa)) = \text{diag}(\kappa, \kappa^{-1})$ or $\rho(\mathbf{t}_{1,1}(\kappa)) = \text{diag}(\kappa^{-1}, \kappa)$, defining $\chi_V = \chi_V^+ \cup \chi_V^-$.

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The local data of ρ is defined by $a^+ = (e_0, a_3 = \text{tr}(M_3), a_4 = \text{tr}(M_4))$ or $a^- = (e_0^{-1}, a_3 = \text{tr}(M_3), a_4 = \text{tr}(M_4))$.

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The coordinates (a^+, x^+) define a map Tr_V^+ , invertible for a generic a , from χ_V^+ to the family affine cubic surface $\mathcal{C}_V(b^+)$ defined by

$$F_V(b^+, x) = x_1 x_2 x_3 + x_1^2 + x_2^2 - b_1^+ x_1 - b_2^+ x_2 - b_3^+ x_3 + b_4^+ = 0,$$

where $b_1^+ = a_3 + e_0 a_4$, $b_2^+ = a_4 + e_0 a_3$, $b_3^+ = e_0$, $b_4^+ = e_0^2 + e_0 a_3 a_4 + 1$.

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We also have a similar map $Tr_V^- : \chi_V^- \rightarrow \mathcal{C}_V(b^-)$ defined by $x_1^- = M_3[1, 1], x_2^- = M_4[1, 1], x_3^- = x_3^-$.

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Expected results: for $J = VI, V$, etc... :

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For the general case?

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Similar to the case $J = VI$:

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Proposition [Ramis, P.], [Klimes]

$$h_b : \begin{cases} x'_1 = -x_1 + x_2x_3 + x_1x_3^2 - \theta_2x_3 + \theta_1 \\ x'_2 = -x_2 - x_1x_3 + \theta_2 \\ x'_3 = x_3 \end{cases}$$

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Remark. The tame dynamics are always *polynomial* dynamics on χ in trace coordinates.

The confluent morphisms.

First description: M. Klimes.

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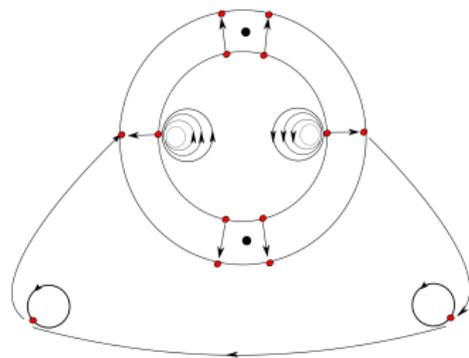
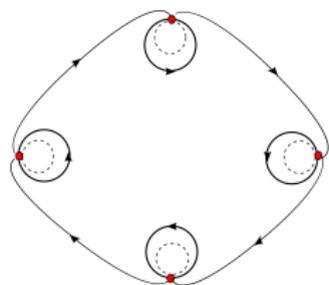
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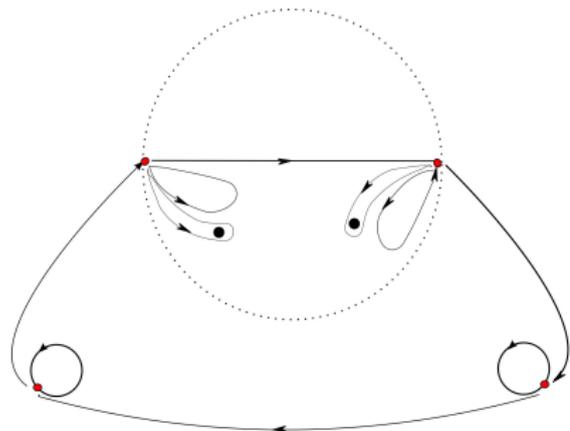
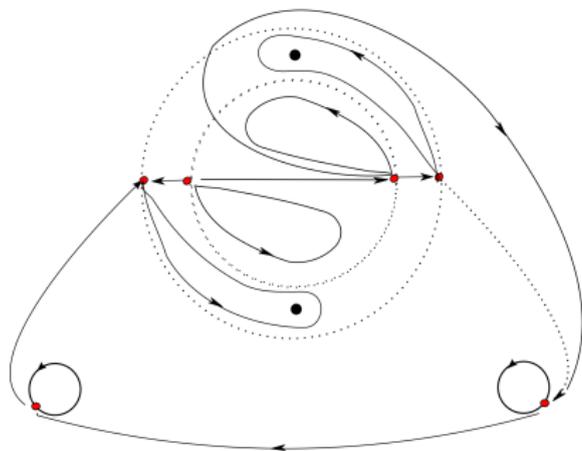
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$$\varphi(\kappa) : \pi_1^{VI}(X, S_{VI}) \rightarrow \pi_1^{V, \kappa}(X, S_V)$$

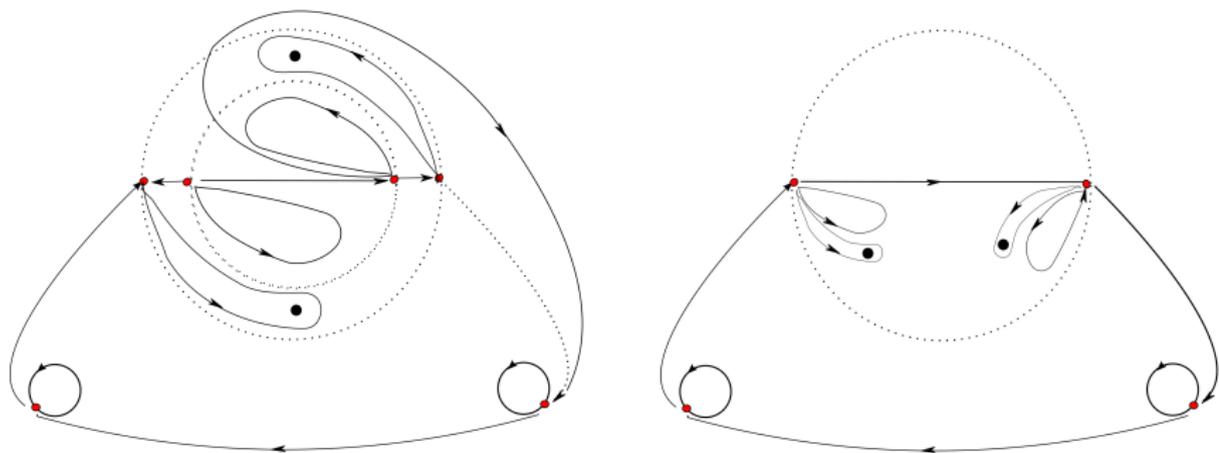
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$$\varphi_\kappa(\gamma_{1,1}) = \sigma_1 \cdot t_{1,1}(\kappa),$$

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For the other generators : $\varphi_\kappa(\gamma_{i,j})$ is defined by the figure above.

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Theorem. *The morphisms $\Phi(\kappa)^\pm : \chi_V^\pm(a) \rightarrow \chi_{VI}(a_\kappa) : \rho \rightarrow \rho \circ \varphi_\kappa$ are generically invertible (on a Zariski open set).*

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Idea of the proof. We want to construct an inverse of

$$\Phi(\kappa) : [U_1, M_0, U_2, M_3, M_4] \mapsto [M_{1,\kappa}, M_{2,\kappa}, M_3, M_4] = [U_1 D_\kappa, D_\kappa^{-1} M_0 U_2, M_3, M_4].$$

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We use the LDU decomposition in SL_2 : If $a \neq 0$,

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ l & 1 \end{pmatrix} \cdot \begin{pmatrix} e & 0 \\ 0 & e^{-1} \end{pmatrix} \cdot \begin{pmatrix} 1 & u \\ 0 & 1 \end{pmatrix} : e = a, l = c/a, u = b/a.$$

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$U_1 M_0 U_2$ is a representation through φ_κ of a loop around the 2 confluent singularities s_1 et s_2 . Therefore:

- $U_1 M_0 U_2$ is the LDU decomposition of a matrix conjugated to $M_{1,\kappa} M_{2,\kappa}$.
- its diagonal component D is $\begin{pmatrix} e_{1,\kappa} e_{2,\kappa} & 0 \\ 0 & e_{1,\kappa}^{-1} e_{2,\kappa}^{-1} \end{pmatrix}$.

Lemma. *Let $M_1, M_2, \neq \pm I$, with eigenvalues (e_1, e_1^{-1}) et (e_2, e_2^{-1}) . Suppose that the eigenvectors related to (M_1, e_1) et (M_2, e_2^{-1}) are independent. There exists a unique matrix $M = P^{-1} M_1 M_2 P$ whose LDU decomposition satisfies $D = \text{diag}(e_{1,\kappa} e_{2,\kappa}, e_{1,\kappa}^{-1} e_{2,\kappa}^{-1})$.*

(P is obtained by using the "mixed" basis induced by the hypothesis.)

The confluent morphisms.

In trace coordinates, we recover the formulas of M. Klimes:

$\Phi_\kappa = \varphi_\kappa^* : \chi_V(\mathbf{a}) \rightarrow \chi_{VI}(\mathbf{a}_\kappa)$ is given by

$$\begin{cases} x_{1,\kappa} = e_0^{-1} \kappa x_1 + \kappa^{-1} x_2 \\ x_{2,\kappa} = -e_0^{-1} \kappa x_1 x_3 + \kappa^{-1} x_1 - e_0^{-1} \kappa x_2 + a_3 \kappa + a_4 e_0^{-1} \kappa \\ x_{3,\kappa} = x_3. \end{cases}$$

Φ_κ is invertible outside the line $L_{e_1, \kappa, e_2, \kappa}$ and Φ_κ^{-1} is given by

$$\begin{cases} x_1 = (-\kappa x_{1,\kappa} - e_0 \kappa^{-1} x_{2,\kappa} + a_3 e_0 + a_4)(x_{3,\kappa} - c_{e_1, \kappa, e_2, \kappa})^{-1} \\ x_2 = (\kappa x_{1,\kappa} x_{3,\kappa} - e_0 \kappa^{-1} x_{1,\kappa} + \kappa x_{2,\kappa} - a_3 \kappa^2 - a_4 \kappa^2 e_0^{-1})(x_{3,\kappa} - c_{e_1, \kappa, e_2, \kappa})^{-1} \\ x_3 = x_{3,\kappa}. \end{cases}$$

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We transfer the dynamics $\langle h_{i,j} \rangle$ of Painlevé VI on χ_V :
 $g_{i,j}(\kappa) := \Phi(\kappa)^{-1} \circ h_{i,j} \circ \Phi(\kappa)$. We obtain:

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$$\begin{cases} X_1 = \frac{e_0}{x_2} \\ X_2 = x_2 + \frac{\kappa^2}{x_2} - e_0^{-1} \kappa^2 x_1 \\ X_3 = -\kappa^2 x_2^2 x_3 + (e_0^{-2} \kappa^2 - \kappa^{-2}) x_1 x_2 - 2e_0^{-1} x_2^2 + \\ \quad + (e_0^{-1} b_2 \kappa^{-2} b_1) x_2 - (e_0^{-1} \kappa^2 + e_0 \kappa^{-2}) \end{cases}$$

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- $g_{3,1}(\kappa)$ is a rational dynamics, defined by: $g_{1,2} \circ g_{2,3}(\kappa) \circ g_{3,1}(\kappa) = id$.

The confluent dynamics on χ_V .

We transfer the dynamics $\langle h_{i,j} \rangle$ of Painlevé VI on χ_V :

$g_{i,j}(\kappa) := \Phi(\kappa)^{-1} \circ h_{i,j} \circ \Phi(\kappa)$. We obtain:

- $g_{1,2}(\kappa)$ do not depend on κ and coincide with the tame dynamics on χ_V .
- $g_{2,3}(\kappa)$ is a rational dynamics:

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Remark. The family $t_{2,3}(\kappa)$ defined by $g_{2,3}(\kappa) = g_{2,3}(1) \circ t_{2,3}(\kappa)$ is multiplicative: $t_{2,3}(\kappa \kappa') = t_{2,3}(\kappa) \circ t_{2,3}(\kappa')$, and can be defined as the flow of a complete vector field.

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- $\mathcal{C}_V(b) \simeq_{bir} \mathbb{C}^2$ by the restriction of $(x_1, x_2, x_3) \rightarrow (x_1, x_2)$ to $\mathcal{C}_V(b)$, because $x_3 = r(x_1, x_2)$, with r rational.

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- $(\mathcal{C}_V(b), \omega_V(b)) \simeq_{bir, sympl} (\mathbb{C}^2, \omega_{log})$, $\omega_{log} = \frac{du}{u} \wedge \frac{dv}{v}$: $(y_1, z_1) = (x_1, x_1 x_2 - e_0)$ is a birational symplectic isomorphism (a log-canonical system of coordinates).

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The dots terms are obtained by using the following "exchange" relations:

$$y_k y_{k+1} = P(z_k) \text{ with } P(t) = t + e_0$$

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Remark. $z_1 z_2 z_3 = 0$ is the equation of 12 lines in $\mathcal{C}_V(b)$.

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Proposition. The log-canonical sequence satisfies the Laurent property.

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- $B_1^{\natural} = \langle U_1, T_1 \rangle$. B_1^{\natural} is also a meta-abelian group which contains U_1 , but it contains only a maximal torus of rank 1. B_1^{\natural} is a Borel of rank 1.

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- We consider a log-canonical triple (z, y, z') .

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Remark. $\text{Dyn}(\mathcal{C}_V(b))$ contains all the T_y and all the s_z .

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If we extend both $Conf$ and Dyn by this element b_{y_2} , $Conf^\# = Dyn^\#$.

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(This was conjectured by J.P. Ramis in 2010).

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- all the morphisms RH_J and Tr_J are symplectic morphisms;
- for generic parameters, the Malgrange groupoid of the Painlevé foliations is maximal.

Thank you for your attention.

HAPPY NEW YEAR!